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Let R be a Bezout domain with identity $e \neq 0$, i.e. R is an integral domain in which every finite generated ideal is principal. Further, let $R_{m,n}$ denote the set of $m \times n$ matrices over R , and $GL(n, R)$ be the set of $n \times n$ invertible matrices over R . In what follows, I_n is the identity $n \times n$ matrix, $0_{m,k}$ is the zero $m \times k$ matrix, $d_i(A) \in R$ is an ideal generated by the i -th order minors of the matrix $A \in R_{m,n}$, $i = 1, 2, \dots, \min\{m, n\}$.

Let $A \in R_{m,n}$ and $B \in R_{m,k}$ be nonzero matrices. Consider the nonhomogeneous matrix equation

$$AX = B, \tag{1}$$

where X is unknown matrix in $R_{n,k}$. Denote by $A_B = [A \ B] \in R_{m,n+k}$ the extended matrix of the linear equations (1). It is known (see [1], [3], [4], [6]) that the equation (1) over a Bezout domain R is solvable if and only if $\text{rank } A = \text{rank } A_B = r$ and $d_i(A) = d_i(A_B)$ for all $i = 1, 2, \dots, r$.

The problem of solvability of the equation (1) has drawn the attention of many mathematicians (see [1]–[12] and references therein). This is explained not only by the theoretical interest to this problem ([1], [3], [4], [6], [8]–[11]), but also by the existence of numerous applied problems connected with the necessity of solution of linear matrix equations ([2], [5], [7], [12]). It may be noted, that the equation (1) over Bezout domains is important in automatic control theory [2].

1. On application of the Hermite Normal Form. In the Bezout domain R we fix a set of non-associated elements \tilde{R} . Every non-associated element $a \in \tilde{R}$ we associated with a complete system of residues modulo ideal (a) . Let $A \in R_{m,n}$ and $\text{rank } A = r$. Further, we assume that the first row of the matrix A is nonzero. For the matrix A there exists $W \in GL(n, R)$ such that

$$AW = H_A = \begin{bmatrix} H_1 & 0_{m_1, n-1} \\ H_2 & 0_{m_2, n-2} \\ \dots & \dots \\ H_r & 0_{m_r, n-r} \end{bmatrix} = [H(A) \ 0_{m, n-r}]$$

is a lower block-triangular matrix, where $H(A) \in R_{m,r}$, $H_1 = \begin{bmatrix} h_1 \\ * \end{bmatrix} \in R_{m_1,1}$, $H_2 = \begin{bmatrix} h_{21} & h_2 \\ * & * \end{bmatrix} \in R_{m_2,2}$,

\dots , $H_r = \begin{bmatrix} h_{r1} & \dots & h_{r, r-1} & h_r \\ * & * & * & * \end{bmatrix} \in R_{r,r}$ and $m_1 + m_2 + \dots + m_r = m$. The elements h_i belong to the

set of non-associated elements \tilde{R} for all $i = 1, 2, \dots, r$. Moreover, in the first rows $[h_{i1} \ \dots \ h_{i, i-1} \ h_i]$ of the matrices H_i , $i \geq 2$, the elements h_{ij} belong to a complete system of residues modulo ideal (h_i) for all $j = 1, 2, \dots, i-1$. The lower block-triangular matrix H_A is called the (right) Hermite normal form of the matrix A and it is uniquely defined for A (see [3]).

In this parch we propose necessary and sufficient conditions of solvability for the equation (1) over a Bezout domain in terms of the Hermite normal forms of $m \times (n+k)$ matrices $[A \ 0_{m,k}]$ and $[A \ B]$. A method for finding its solutions is also given. In what follows, we assume that the first row of the matrix A is nonzero.

Theorem 1. *Let $A \in R_{m,n}$ and $B \in R_{m,k}$. The matrix equation $AX = B$ is solvable over a Bezout domain R if and only if the Hermite normal forms of matrices $[A \ 0_{m,k}]$ and $[A \ B]$ are coincide.*

It is easy to see that matrix equation (1) is solvable over a Bezout domain R if and only if the matrix equation $H(A)Y = B$ is solvable over R . Let $Y_0 \in R_{r,k}$ be the solution of $H(A)Y = B$. Then

for arbitrary matrix $P \in \mathbb{R}_{n-r,k}$ the matrix $X_P = W^{-1} \begin{bmatrix} Y_0 \\ P \end{bmatrix}$ is a general solution of equation (1).

Theoretically speaking, the solution $X_0 = W^{-1} \begin{bmatrix} Y_0 \\ 0_{m-r,n} \end{bmatrix}$ of equation (1) can be written as the matrix expression $X_0 = TX_P$, where $T \in \mathbb{R}_{n,n}$. Thus, X_P is the right divisor of X_0 for an arbitrary matrix $P \in \mathbb{R}_{n-r,k}$. Given the solution X_0 , we determine all possible ranks of other solutions of the equation (1), i.e. $\text{rank}B \leq \text{rank}X_P \leq n + \text{rank}B - \text{rank}A$.

2. A method of matrix transformations. In this part we apply matrix transformations for established conditions under which the equation (1) is solvable.

Let $A \in \mathbb{R}_{m,n}$ and $B \in \mathbb{R}_{m,k}$ be nonzero matrices and let $\text{rank}A = r \geq 1$. For A there exist matrices $U \in GL(m, \mathbb{R})$ and $V \in GL(n, \mathbb{R})$ such that $UAV = \begin{bmatrix} C & 0_{r,n-r} \\ 0_{m-r,r} & 0_{m-r,n-r} \end{bmatrix}$, where $C \in \mathbb{R}_{r,r}$. It is clear that $\det C = c \neq 0$. In what follows $C^* = \text{Adj}C$ means the classical adjoint matrix of the matrix C , i.e. $C^*C = cI_r$. Based on the above, we obtain the following theorem.

Theorem 2. *The matrix equation $AX = B$ is solvable over a Bezout domain \mathbb{R} if and only if $UB = \begin{bmatrix} D \\ 0_{m-r,k} \end{bmatrix}$, where $D \in \mathbb{R}_{r,k}$, and $C^*D = cG$, where $G \in \mathbb{R}_{r,k}$.*

If the equation $AX = B$ is solvable, then for arbitrary matrix $Q \in \mathbb{R}_{m-r,k}$ the matrix $X_Q = U^{-1} \begin{bmatrix} G \\ Q \end{bmatrix}$ is a general solution of equation $AX = B$.

From Theorem 2 we obtain the following comment. Let $A, B \in \mathbb{R}_{m,n}$ be nonzero matrices and let $\text{rank}A < n$. Suppose the matrix equation $AX = B$ is solvable and $X_Q \in \mathbb{R}_{n,n}$ is its general solution. Then $AX = B$ has solutions $\tilde{X}_i \in \mathbb{R}_{n,n}$, $i = 1, 2, \dots$, such that $X_Q = \tilde{X}_i T_i$, where $T_i \in \mathbb{R}_{n,n}$.

Presented results above can be extended to linear nonhomogeneous equations over commutative rings of a more general algebraic nature.

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