

Nijenhuis Geometry

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Albert Nijenhuis



Albert Nijenhuis (November 21, 1926 – February 13, 2015), Dutch-American mathematician who specialised in differential geometry and the theory of deformations in algebra and geometry, and later worked in combinatorics.

Alma mater: University of Amsterdam

Doctoral advisor: Prof. Jan Arnoldus Schouten

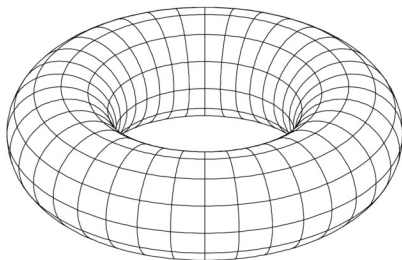
https://en.wikipedia.org/wiki/Albert_Nijenhuis

What is GEOMETRY?

Space, manifold M^n

+

Structure



Structure is usually defined by means of a tensor, like g_{ij} , ω_{ij} , or P^{ij}

Naively, in coordinates, the geometric structure is defined by means of a matrix $A = (a_{ij}(x))$ whose entries depend on coordinates $x = (x^1, \dots, x^n)$ and satisfy some algebraic and differential conditions.

Nijenhuis geometry. Our motivation

Definition

By **Nijenhuis operators** we understand $(1, 1)$ -tensors $L = (L^i_j(x))$ with vanishing Nijenhuis torsion:

$$\mathcal{N}_L(\xi, \eta) = L^2[\xi, \eta] + [L\xi, L\eta] - L[L\xi, \eta] - L[\xi, L\eta] = 0.$$

A manifold M endowed with such an operator it is called a **Nijenhuis manifold**.

Motivation

- ▶ Riemannian, Kähler, symplectic, Poisson... **Nijenhuis geometry** is the next natural candidate to continue this list.
- ▶ In the context of the **bi-Hamiltonian formalism**, Nijenhuis operators occur as recursion operators.
- ▶ In the theory of **integrable geodesic flows**, projectively equivalent Riemannian metrics are related by means of a Nijenhuis operator.
- ▶ In **topology of integrable systems**, singularities of Lagrangian fibrations related to bi-Hamiltonian systems correspond to singular points of the corresponding Nijenhuis recursion operators.
- ▶ In **integrable systems on Lie algebras**, algebraic Nijenhuis operators are used in the study of Lie-Poisson pencils.

Elementary examples

- ▶ Constant operator:

$$L(x) = (L_j^i)$$

with L_j^i being constant for all i, j

- ▶ Scalar operator:

$$L(x) = f(x) \cdot \text{Id},$$

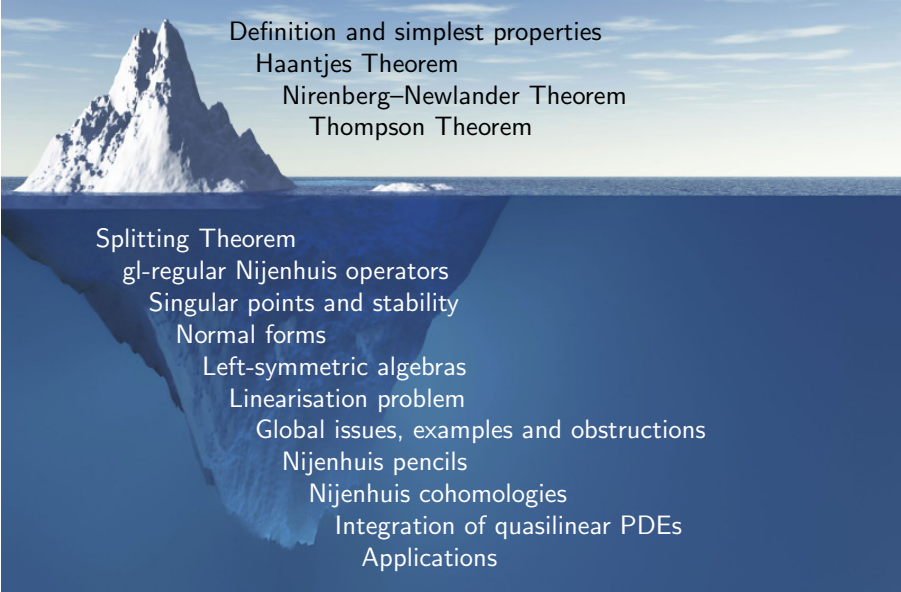
where $f(x)$ is an arbitrary smooth function

- ▶ Complex structure

$$\text{▶ } L(x) = \begin{pmatrix} x_1 & & & & \\ & x_2 & & & \\ & & \ddots & & \\ & & & & x_n \end{pmatrix}$$

$$\text{▶ } L(x) = \begin{pmatrix} x_5 & x_4 & x_3 & x_2 & x_1 \\ & x_5 & x_4 & x_3 & x_2 \\ & & x_5 & x_4 & x_3 \\ & & & x_5 & x_4 \\ & & & & x_5 \end{pmatrix}$$

Nijenhuis Geometry

An iceberg floating in the ocean. The tip of the iceberg, which is above the water line, is white and jagged, representing the visible part of the subject. The much larger part of the iceberg, which is submerged and dark blue, represents the deeper, more complex aspects of the subject. The text is arranged to mirror this metaphor, with the visible part above the water and the submerged part below.

Definition and simplest properties
Haantjes Theorem
Nirenberg–Newlander Theorem
Thompson Theorem

Splitting Theorem
gl-regular Nijenhuis operators
Singular points and stability
Normal forms
Left-symmetric algebras
Linearisation problem
Global issues, examples and obstructions
Nijenhuis pencils
Nijenhuis cohomologies
Integration of quasilinear PDEs
Applications

Research agenda

The ultimate goal of our research programme is to answer three fundamental questions:

- (A) **Local description:** to what form can one bring a Nijenhuis operator near almost every point by a local coordinate change?
- (B) **Singular points:** what does it mean for a point to be generic or singular in the context of Nijenhuis geometry? What singularities are non-degenerate/stable? How do Nijenhuis operators behave near non-degenerate and stable singular points?
- (C) **Global properties:** what restrictions on a Nijenhuis operator are imposed by the topology of the underlying manifold? And conversely, what are topological obstructions to a Nijenhuis manifold carrying a Nijenhuis operator with specific properties?

as well as to work on

- (D) **Applications of Nijenhuis Geometry:** in geometry, algebra and mathematical physics

Fundamental property of the characteristic polynomial of a Nijenhuis operator

Here and below L denotes a Nijenhuis operator.

Theorem

Let $\sigma_1, \dots, \sigma_n$ be the coefficients of the characteristic polynomial of L :

$$\chi(t) = \det(t \cdot \text{Id} - L(x)) = t^n - \sum_{k=1}^n \sigma_k(x) t^{n-k}.$$

Then in any local coordinate system x_1, \dots, x_n the following matrix relation hold:

$$J(x) L(x) = S_\chi(x) J(x), \quad \text{where } S_\chi(x) = \begin{pmatrix} \sigma_1(x) & 1 & & \\ \vdots & 0 & \ddots & \\ \sigma_{n-1}(x) & \vdots & \ddots & 1 \\ \sigma_n(x) & 0 & \dots & 0 \end{pmatrix}$$

and $J(x) = \left(\frac{\partial \sigma_i}{\partial x_j} \right)$ is the Jacobi matrix of the collection of functions $\sigma_1, \dots, \sigma_n$ w.r.t. local coordinates x_1, \dots, x_n .

Two corollaries

Corollary

Assume that the coefficients of the characteristic polynomial of L are functionally independent almost everywhere on M . Then L can be uniquely reconstructed from them:

$$L(x) = J^{-1}(x)S_\chi(x)J(x).$$

Corollary

Assume that the coefficients of the characteristic polynomial of L are functionally independent in a neighbourhood of a point $p \in M$ (i.e., $\det J(x) \neq 0$)¹. Then there exists a local coordinate system u^1, \dots, u^n in which L takes the following form

$$L(u) = \begin{pmatrix} u^1 & 1 & & \\ \vdots & 0 & \ddots & \\ u^{n-1} & \vdots & \ddots & 1 \\ u^n & 0 & \dots & 0 \end{pmatrix}.$$

¹Such points are called **differentially non-degenerate**.

Left-symmetric algebras and linearisation

Consider an operator $L = \left(a_{jk}^i x^k \right)$ whose components are linear functions in coordinates x^1, \dots, x^n .

Observation. L is Nijenhuis if and only if a_{jk}^i are structure constants of a left-symmetric algebra.

Reminder: An algebra $(\mathfrak{a}, *)$ is called *left-symmetric* (or *pre-Lie*) if:

$$\xi * (\eta * \zeta) - (\xi * \eta) * \zeta = \eta * (\xi * \zeta) - (\eta * \xi) * \zeta, \quad \text{for all } \xi, \eta, \zeta \in \mathfrak{a}.$$

Linearisation of a Nijenhuis operator at a singular point. Let L be a Nijenhuis operator in a neighbourhood of a point $q \in M$ such that $L(q) = 0$. In local coordinates $x = (x_1, \dots, x_n)$, centred at q , we can expand $L(x)$ into Taylor series:

$$L(x) = 0 + L_1(x) + L_2(x) + \dots$$

where L_k is homogeneous of degree k in x_1, \dots, x_n .

Then the first term $L_1 = L_{\text{lin}}$ defines a Nijenhuis operator in variables x_1, \dots, x_n , called the *linearisation* of L at q .

Conclusion:

Left symmetric algebras \leftrightarrow linearisations of Nijenhuis structures

Definition

A left-symmetric algebra \mathfrak{a} is *non-degenerate* if every Nijenhuis operator L such that $L_{\text{lin}} \simeq \mathfrak{a}$, is linearisable, i.e., L is isomorphic to L_{lin} .

Theorem (A. Konyaev)

In dimension two, there are 12 types of real LSAs, six of which are non-degenerate in the smooth sense (with parameters appropriately chosen). In the real analytic case, the list of non-degenerate LSAs is different (slightly larger).

Theorem (Real analytic or formal)

Let $L(x) = L_{\text{lin}}(x) + \dots$ with

$$L_{\text{lin}}(x) = \text{diag}(x_1, x_2, \dots, x_n).$$

Then $L(x)$ is linearisable, i.e., the diagonal LSA is non-degenerate. In other words, there exists a real analytic (formal) change of variables $x \mapsto y$ such that in the new coordinates

$$L(y) = \text{diag}(y_1, y_2, \dots, y_n).$$

Regular Nijenhuis manifolds

Definition

An operator L is called *gl-regular*, if each eigenvalue of L possesses only one eigenvector (up to proportionality). Equivalently, the operators $\text{Id}, L, L^2, \dots, L^{n-1}$ are linearly independent.

Question: What is a local structure of a gl-regular Nijenhuis manifold?

Theorem (Real analytic case)

Let L be a gl-regular Nijenhuis operator. Then there exist local coordinate systems $u = (u_1, \dots, u_n)$ and $v = (v_1, \dots, v_n)$ in which L reduces to the first and second companion forms:

$$L(u) = \begin{pmatrix} \sigma_1 & 1 & & \\ \vdots & 0 & \ddots & \\ \sigma_{n-1} & \vdots & \ddots & 1 \\ \sigma_n & 0 & \dots & 0 \end{pmatrix} \quad \text{and} \quad L(v) = \begin{pmatrix} 0 & 1 & & \\ \vdots & \ddots & \ddots & \\ 0 & \dots & 0 & 1 \\ \sigma_n & \sigma_{n-1} & \dots & \sigma_1 \end{pmatrix},$$

where σ_i are the coefficients of the characteristic polynomial of L in the corresponding coordinate system.

Some global results

Theorem

A Nijenhuis operator on a closed connected manifold cannot have non-constant complex eigenvalues.

Theorem

A Nijenhuis operator on a closed connected manifold cannot have differentially non-degenerate critical points.

Theorem

1. *Let M^2 be an orientable closed surface and $M^2 \not\cong T^2$ (torus). Then on M^2 there are **no \mathfrak{gl} -regular Nijenhuis operators** except for $L = \alpha \text{Id} + \beta J$, where J is a complex structure and $\alpha, \beta \in \mathbb{R}$, $\beta \neq 0$.*
2. *Let M^2 be a non-orientable closed surface and $M^2 \not\cong K^2$ (Klein bottle). Then on M^2 there are **no \mathfrak{gl} -regular Nijenhuis operators** at all.*

Applications to geodesically equivalent metrics

Two (pseudo)-Riemannian metrics g and \bar{g} are called *geodesically equivalent* if they share the same (unparametrised) geodesics.

Observation (Sinjukov). A manifold endowed with a pair of such metrics carries a natural Nijenhuis structure defined by the operator

$$L = \left| \frac{\det \bar{g}}{\det g} \right|^{\frac{1}{n+1}} \bar{g}^{-1} g.$$

The *geodesic equivalence condition* in terms of L :

$$\nabla_{\xi} L = \frac{1}{2} (u \otimes \text{d tr } L + (u \otimes \text{d tr } L)^*).$$

Here L serves as a partner of the metric g : we say that g and L are *geodesically compatible*, if this relation holds.

Important open problem. What happens *at singular points* (i.e., at those where the algebraic type of L changes, e.g., the eigenvalues of L collide)? Which singularities are allowed?

Theorem

Let L be a \mathfrak{gl} -regular real analytic Nijenhuis operator. Then (locally) there exists a pseudo-Riemannian metric g that is geodesically compatible with L . Moreover, such a metric g can be defined explicitly in terms of the second companion form of L .

Recall that an operator M is called a *symmetry* of L if these operators commute in algebraic sense, i.e. $ML = LM$, and the following relation holds:

$$M[L\xi, \xi] + L[\xi, M\xi] - [L\xi, M\xi] = 0 \quad \text{for any vector field } \xi.$$

A symmetry M is called *strong* if

$$\langle L, M \rangle(\xi, \eta) \stackrel{\text{def}}{=} M[L\xi, \eta] + L[\xi, M\eta] - [L\xi, M\eta] - LM[\xi, \eta] = 0 \quad \text{for all } \xi, \eta.$$

Theorem

Let L and g be geodesically compatible. Assume that M is g -self-adjoint and is a strong symmetry of L , then L and gM are geodesically compatible.

Moreover, if L is \mathfrak{gl} -regular, then every metric \tilde{g} geodesically compatible with L is of the form $\tilde{g} = gM$, where M is a (strong) symmetry of L .

Open problems

- ▶ Describe the topology of closed gl -regular Nijenhuis manifolds.
- ▶ Construct real analytic examples of Nijenhuis operators on closed two-dimensional surfaces whose eigenvalues are real and generically distinct.
- ▶ Describe/classify maximal Nijenhuis pencils.
- ▶ Local classification of gl -regular Nijenhuis operators.
- ▶ Classify left-symmetric algebras of low dimension.
- ▶ Find/construct examples of non-degenerate LSAs of arbitrary dimension.
- ▶ Describe/classify LSAs with algebraically independent coefficients of the characteristic polynomial.
- ▶ etc.

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Thanks for your attention

