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Let's suppose that $\mathbb{H}^2 = \{(x, y) \mid y > 0\}$ is an upper half-plane with the Riemannian metric $\frac{dx^2 + dy^2}{y^2}$. It is called a hyperbolic plane and has a constant negative Gaussian curvature -1 . Besides,

\mathbb{H}^2 is a Hadamard space, which is a complete Riemannian manifold of nonpositive sectional curvature.

Between two any points $x, y \in \mathbb{H}^2$ there is a unique geodesic $\sigma_{x,y}$. So we can define a notion of a *geodesically convex* (or just *convex*) set in hyperbolic plane — it is a set that for two arbitrary points x and y of its $\sigma_{x,y}$ belongs to this set. Particularly, the mapping

$$\rho : \mathbb{H}^2 \times \mathbb{H}^2 \rightarrow \mathbb{R}, \rho(x, y) = \ell(\sigma_{x,y}), x, y \in \mathbb{H}^2,$$

where ℓ denotes a length of curve in \mathbb{H}^2 , satisfies all the axioms of metric space.

We also can define a notion of convex function in \mathbb{H}^2 .

Definition 1. We will call a parametrization $\gamma : [0, 1] \rightarrow \mathbb{H}^2$ of the geodesics between points a and b in \mathbb{H}^2 , $\gamma(0) = a$, $\gamma(1) = b$, *standard*, if for all $\alpha \in (0; 1)$ the equality

$$\rho(a, \gamma(\alpha)) = \alpha \ell$$

holds. Here ℓ denotes a length of the appropriate geodesics.

Definition 2. A function $f : \mathbb{H}^2 \rightarrow \mathbb{R}$ is called *convex* in a convex set $A \subset \mathbb{H}^2$, if for arbitrary points $x_1, x_2 \in A$ and a standard parametrization $\gamma : [0, 1] \rightarrow \mathbb{H}^2$ of the geodesics between them, $\gamma(0) = x_2$, $\gamma(1) = x_1$, next inequality holds:

$$\forall \alpha \in [0, 1] : f(\gamma(\alpha)) \leq \alpha f(x_1) + (1 - \alpha)f(x_2). \quad (1)$$

Definition 3. Let's fix in \mathbb{H}^2 any mutually distinct points x_1, \dots, x_N , where $N \in \mathbb{N}$, and such positive numbers w_1, \dots, w_N , a that $\sum_{k=1}^N w_k = 1$. *Open weighted N -foci ball*, or *weighted N -foci ball*, is a set

$$A = \{x \in \mathbb{H}^2 \mid w_1 \rho(x, x_1) + \dots + w_N \rho(x, x_N) < a\}, \quad (2)$$

where x_1, \dots, x_N are called *foci of the weighted N -foci ball*, a is called *a radius of the weighted N -foci ball*, w_1, \dots, w_N are called *weights of the foci x_1, \dots, x_N* .

We can define closed weighted N -foci balls the same way, having replaced the symbol “ $<$ ” by the symbol “ \leq ” in the formula (2).

Let's fix any point $x_0 \in \mathbb{H}^2$ and define the distance function for it:

$$f : \mathbb{H}^2 \rightarrow \mathbb{R}, f(x) = \rho(x, x_0), x \in \mathbb{H}^2.$$

Theorem 4. *The distance function f is convex in the hyperbolic plane \mathbb{H}^2 .*

It is known, that such a function is convex in any Hadamard space [2]. In this work we got a direct proof of convexity of f for the case of the hyperbolic plane.

From the convexity of f we obtain another result.

Theorem 5. *All open and closed weighted N -foci balls are geodesically convex sets in the hyperbolic plane \mathbb{H}^2 .*

We also proved geodesical convexity of 1-foci ball, which is a hyperbolic ball, with geometrical methods.

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