

Stability of vertical minimal surfaces in three-dimensional sub-Riemannian manifolds

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27 May, 2024

A *sub-Riemannian manifold* is a smooth manifold M together with a completely non-integrable smooth distribution \mathcal{H} on M (it is called a *horizontal distribution*) and a smooth field of Euclidean scalar products $\langle \cdot, \cdot \rangle_{\mathcal{H}}$ on \mathcal{H} (it is called a *sub-Riemannian metric*). In particular, $\langle \cdot, \cdot \rangle_{\mathcal{H}}$ can be constructed as the restriction of some Riemannian metric $\langle \cdot, \cdot \rangle$ on M to \mathcal{H} . Here we will assume that all sub-Riemannian structures are of this form.

Let Σ be a smooth oriented surface in a three-dimensional sub-Riemannian manifold M . If N_h is the orthogonal projection of the unit normal field N of Σ (in the Riemannian sense) onto \mathcal{H} and $d\Sigma$ is the Riemannian area form of Σ , then the *sub-Riemannian area* of a domain $D \subset \Sigma$ is defined as

$$A(D) = \int_D |N_h| d\Sigma.$$

The *normal variation* of the surface Σ defined by a smooth function u is the map

$$\varphi : \Sigma \times I \rightarrow M : \varphi_s(p) = \exp_p(su(p)N(p)),$$

where I is an open neighborhood of 0 in \mathbb{R} and \exp_p is the Riemannian exponential map at p . In other words, we construct the variation in the traditional Riemannian way by drawing the geodesic through each point $p \in \Sigma$ in the direction of the normal vector $u(p)N(p)$.

Denote

$$A(s) = \int_{\Sigma_s} |N_h| d\Sigma_s,$$

where $\Sigma_s = \varphi_s(\Sigma)$. Then $A'(0)$ is called the first (*normal*) *area variation* defined by φ , and $A''(0)$ is called the *second* one.

A surface Σ is called *minimal* if $A'(0) = 0$ for any normal variations with compact support in $\Sigma \setminus \Sigma_0$, where $\Sigma_0 = \{p \in \Sigma \mid N_h(p) = 0\}$ is the *singular set* of Σ . Note that here we also follow the Riemannian tradition by defining minimal surfaces as stationary points of the sub-Riemannian area functional.

A minimal surface Σ is called *stable* if $A''(0) \geq 0$ for any normal variations with compact support in $\Sigma \setminus \Sigma_0$.

We will call a surface Σ in a three-dimensional sub-Riemannian manifold *vertical* if $T_p\Sigma \perp \mathcal{H}_p$ for each $p \in \Sigma$, that is, $N \in \mathcal{H}$. In particular, for such surfaces $N_h = N$ and $\Sigma_0 = \emptyset$.

Proposition

Let Σ be a vertical surface in a three-dimensional sub-Riemannian manifold M . Then its first normal area variation defined by a smooth function u with compact support equals

$$A'(0) = - \int_{\Sigma} 2Hu \, d\Sigma,$$

where H is the Riemannian mean curvature of Σ .

Corollary

A vertical surface is minimal in the sub-Riemannian sense if and only if it is minimal in the Riemannian sense.

Proposition

Let Σ be a vertical minimal surface in a three-dimensional sub-Riemannian manifold M . Then its second normal area variation defined by a smooth function u with compact support equals

$$A''(0) = \int_{\Sigma} - (X(u) - \langle \nabla_N X, N \rangle u)^2 +$$

$$+ \underbrace{|\nabla_{\Sigma} u|^2 - (\text{Ric}(N, N) + |B|^2) u^2}_{\text{The Riemannian part}} d\Sigma,$$

where ∇ and Ric are the Riemannian connection and the Ricci tensor of M respectively, X is the unit normal vector field of \mathcal{H} (which is tangent to Σ because it is vertical), ∇_{Σ} and $|B|$ are the Riemannian gradient and the norm of the second fundamental form of Σ respectively.

Corollary

If a vertical minimal surface is stable in the sub-Riemannian sense, it is also stable in the Riemannian sense.

Let us look at some examples.

In [3] A. Hurtado and C. Rosales considered the standard three-dimensional sphere $(S^3, \langle \cdot, \cdot \rangle)$ embedded in the Euclidean space \mathbb{R}^4 with coordinates (x, y, z, w) with the horizontal distribution orthogonal to the Hopf field

$$X = -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} - w \frac{\partial}{\partial z} + z \frac{\partial}{\partial w}$$

(completely non-integrable and left-invariant with respect to the Lie group structure of S^3) and showed that complete connected vertical minimal surfaces are Clifford tori. It is well-known that they are not stable in the Riemannian sense, hence also in the sub-Riemannian sense.

The three-dimensional Heisenberg group \mathbb{H}^1 (also known as the three-dimensional Thurston geometry *Nil*) is the space \mathbb{R}^3 with coordinates (x, y, z) and with the following orthonormal basis of left-invariant vector fields defined by its nilpotent Lie group structure:

$$X_1 = \frac{\partial}{\partial x} - y \frac{\partial}{\partial z}, X_2 = \frac{\partial}{\partial y} + x \frac{\partial}{\partial z}, X_3 = \frac{\partial}{\partial z}.$$

Let the horizontal distribution \mathcal{H} be orthogonal to X_3 . It is completely non-integrable because $[X_1, X_2] = X_3$.

In [2] it was shown by A. Hurtado, M. Ritoré and C. Rosales that a complete connected minimal surface with the empty singular set (in particular, vertical) in \mathbb{H}^1 is stable if and only if it is a vertical (that is, parallel to $X_3 = \frac{\partial}{\partial z}$) Euclidean plane.

Note that there are no other vertical minimal surfaces in \mathbb{H}^1 .

The manifold $\widetilde{E(2)}$ is the universal covering of the proper motions group of the Euclidean plane. This is the space \mathbb{R}^3 with coordinates (x, y, z) and with the following orthonormal basis of left-invariant vector fields defined by its solvable Lie group structure:

$$X_1 = \cos z \frac{\partial}{\partial x} + \sin z \frac{\partial}{\partial y}, X_2 = -\sin z \frac{\partial}{\partial x} + \cos z \frac{\partial}{\partial y}, X_3 = \frac{\partial}{\partial z}.$$

Note that its Riemannian metric is Euclidean and that $[X_3, X_1] = X_2$, so the horizontal distribution \mathcal{H} orthogonal to X_2 is completely non-integrable.

In [1] we proved that all complete connected vertical minimal surfaces in $\widetilde{E(2)}$ are Euclidean planes $z = C$ and standard helicoids. We showed that planes are stable in the sub-Riemannian sense, and it is known that helicoids are not stable in the Riemannian sense, hence also in the sub-Riemannian sense.

The three-dimensional Thurston geometry Sol is the space \mathbb{R}^3 with coordinates (x, y, z) and with the following orthonormal basis of left-invariant vector fields defined by its solvable Lie group structure:

$$X_1 = \frac{1}{\sqrt{2}} \left(e^{-z} \frac{\partial}{\partial x} + e^z \frac{\partial}{\partial y} \right), X_2 = \frac{1}{\sqrt{2}} \left(e^{-z} \frac{\partial}{\partial x} - e^z \frac{\partial}{\partial y} \right),$$
$$X_3 = \frac{\partial}{\partial z}.$$

Note that $[X_2, X_3] = X_1$, so the left-invariant distribution \mathcal{H} orthogonal to X_1 is completely non-integrable. Let us consider a sub-Riemannian structure on Sol such that \mathcal{H} is horizontal.

It follows from the results of L. Masaltsev in [4] that any complete connected vertical minimal surface in Sol is either a Euclidean plane $z = C$ or a "helicoid"

$$(s, t) \mapsto \left(\frac{1}{\sqrt{2}}e^{-t}s + C_1, \frac{1}{\sqrt{2}}e^t s + C_2, t \right).$$

Using this description, we are able to prove the following.

Proposition

All vertical minimal surfaces in Sol are stable in the sub-Riemannian sense and thus in the Riemannian sense.

The three-dimensional Thurston geometry $\widetilde{SL}(2, \mathbb{R})$ can be described as the universal covering of the unit tangent bundle of the hyperbolic plane H^2 with the Sasaki metric, that is, the half-space $\{(x, y, z) \in \mathbb{R}^3 \mid y > 0\}$ with the following orthonormal basis of left-invariant vector fields with respect to its simple Lie group structure:

$$X_1 = y \left(-\sin z \frac{\partial}{\partial x} + \cos z \frac{\partial}{\partial y} \right) + \sin z \frac{\partial}{\partial z},$$

$$X_2 = y \left(-\cos z \frac{\partial}{\partial x} - \sin z \frac{\partial}{\partial y} \right) + \cos z \frac{\partial}{\partial z}, X_3 = \frac{\partial}{\partial z}.$$

In particular, $[X_1, X_2] = -X_3$, so the left-invariant distribution \mathcal{H} orthogonal to X_3 is completely non-integrable. Consider a sub-Riemannian structure on this manifold such that \mathcal{H} is horizontal.

We then obtain the following description.





Theorem

Any complete connected vertical minimal surface in $\widetilde{SL}(2, \mathbb{R})$ has either the parameterization $(s, t) \mapsto (C, s, t)$ or $(s, t) \mapsto \left(C_1 + \frac{1}{C_2} \sin C_2 s, -\frac{1}{C_2} \cos C_2 s, t \right)$ and so is a cylinder over a geodesic in H^2 .

All vertical minimal surfaces in $\widetilde{SL}(2, \mathbb{R})$ are stable in the sub-Riemannian sense and thus in the Riemannian sense.

Thank you!

Дякую за увагу!

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